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UTILITY PATENT APPLICATION TRANSMITTAL

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APPLICATION ELEMENTS

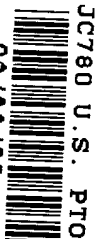
See MPEP chapter 600 concerning utility patent application contents.

1. X Fee Transmittal Form
(Submit an original, and a duplicate for fee processing)
2. X Specification (Total Pages)
(preferred arrangement set forth below)
 - Descriptive Title of the Invention
 - Cross References to Related Applications
 - Statement Regarding Fed sponsored R & D
 - Reference to Microfiche Appendix
 - Background of the Invention
 - Brief Summary of the Invention
 - Brief Description of the Drawings (if filed)
 - Detailed Description
 - Claims
 - Abstract of the Disclosure
3. X Drawings(s) (35 USC 113) (Total Sheets 5)
4. Oath or Declaration (Total Pages)
 - a. Newly Executed (Original or Copy)
 - b. Copy from a Prior Application (37 CFR 1.63(d))
(for Continuation/Divisional with Box 17 completed) (**Note Box 5 below**)
 - i. DELETIONS OF INVENTOR(S) Signed statement attached deleting inventor(s) named in the prior application, see 37 CFR 1.63(d)(2) and 1.33(b).
5. Incorporation By Reference (useable if Box 4b is checked)
The entire disclosure of the prior application, from which a copy of the oath or declaration is supplied under Box 4b, is considered as being part of the disclosure of the accompanying application and is hereby incorporated by reference therein.
6. Microfiche Computer Program (Appendix)

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8. _____ Assignment Papers (cover sheet & documents(s))

9. _____ a. 37 CFR 3.73(b) Statement (where there is an assignee)

_____ b. Power of Attorney

10. _____ English Translation Document (if applicable)

11. _____ a. Information Disclosure Statement (IDS)/PTO-1449

_____ b. Copies of IDS Citations

12. _____ Preliminary Amendment

13. X _____ Return Receipt Postcard (MPEP 503) (Should be specifically itemized)

14. _____ a. Small Entity Statement(s)

_____ b. Statement filed in prior application, Status still proper and desired

15. _____ Certified Copy of Priority Document(s) (if foreign priority is claimed)

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____ Continuation ____ Divisional ____ Continuation-in-part (CIP)
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by

Aviad J. Wertheimer

Simcha Pearl

Date of Deposit: March 29, 2000

(Typed or printed name of person mailing paper or fee)

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Field of Invention

The present invention is directed to network communications, and more specifically, to the transmission of link frames over a home phone line network.

Background

5 The Home Phoneline Networking Alliance (HomePNA) is an incorporated, non-profit association of companies working to bring networking technology to the home. See www.homepna.org. HomePNA envisions bringing Ethernet technology to the home by utilizing existing home phone wiring for the network physical medium. HomePNA provides specifications for the physical layer (PHY), its interface to an Ethernet MAC
10 (Media Access Control), and its interface to the home phone wiring. See the IEEE (Institute of Electrical and Electronic Engineers) 802.3 standard for Ethernet.

15 The position of a HomePNA PHY in relationship to the OSI (Open Systems Interconnection) model is illustrated in Fig. 1. Logical Link Control (LLC) **102** and MAC **104** are implemented in accordance with IEEE 802.3, and HomePNA PHY **106** communicates with MAC **104** via interface **108**. Additional sublayers, and other optional layers, may be added to the layers shown in Fig. 1 so that PHY **106** may provide services to other communication protocols, such as Gigabit Ethernet. In practice, PHY **106** and MAC **104** may be integrated on a single die, so that interface **108** is not readily visible.

20 PHY **106** receives a MAC frame from MAC **104**, strips off the 8 octets of preamble and delimiter from the MAC frame, adds a HomePNA PHY header to form a HomePNA PHY frame, and transmits a PHY frame on physical medium **110**. Fig. 2 illustrates HomePNA PHY framing. A PHY frame comprises Ethernet Packet **202**, and appended to Ethernet Packet **202** is a HomePNA PHY header, comprising SYNC interval **204**, Access ID (Identification) **206**, Silence interval **208**, and PCOM field **210**.

25 A PHY frame is transmitted on physical medium **110** utilizing pulse position modulation (PPM). All PHY symbols transmitted on physical medium **110** comprise a pulse formed of an integer number of cycles of a square wave that has been filtered with a bandpass filter. The position of the pulse conveys the transmitted symbol. Differential signaling is employed, in which a pulse and its negative are transmitted on two wires for
30 each transmitted symbol.

As indicated in Fig. 2, transmission begins with SYNC symbol 0, and Access ID field 206 is coded into seven AID (Access ID) symbols. SYNC symbol 0 may also be denoted as AID symbol 0. Access ID symbols 1 through 4 are used to identify individual stations to enable reliable collision detection. Access ID symbols 5 and 6 are used to transmit remote control management commands. AID symbol 7 is a silence interval.

SYNC symbol 0 and each AID symbol are 129 tics long, where 1 tic is defined as $(7/60)10^{-6}$ seconds, which is approximately 116.667 nanoseconds. AID symbols 1 through 7 begin with a blanking interval of 60 tics, followed by a pulse positioned within one of four time slots to convey two bits of information. The time slots are separated by 20 tics, and are at positions 66, 86, 106, and 126 tics from the beginning of an AID symbol interval. SYNC symbol 0 is composed of a SYNC_START pulse beginning at tic = 0 and a SYNC_END pulse beginning at tic = 126.

In the example of Fig. 2, AID symbols 1 through 4 represent the Access ID word 00101101, where AID symbol 1 represents AID0 = 1 and AID1 = 0, AID symbol 2 represents AID2 = 1 and AID3 = 1, AID symbol 3 represents AID4 = 0 and AID5 = 1, and AID symbol 4 represents AID6 = 0 and AID7 = 0. AID symbols 5 and 6 represent the control word 0001, where AID symbol 5 represents Ctrl0 = 1 and Ctrl1 = 0, and AID symbol 7 represents Ctrl2 = 0 and Ctrl3 = 0.

A collision is detected only during AID symbols 0 through 7. If a transmitting station reads back an AID value that does not match its own, then a collision is indicated, and a JAM signal is transmitted to alert other stations. Non-transmitting stations may also detect non-conforming AID pulses as collisions. Only a transmitting station emits a JAM signal.

Fig. 3 illustrates in more detail MAC-to-HomePNA PHY interface 108. The signals RxD, RxClk, TxD, TxClk, TxEn, CRS, and COL are described in Table 1. HomePNA PHY 106 retains control of the TxClk and RxClk signals for clocking data synchronously in and out of MAC 104.

Table 1 HomePNA PHY-to-MAC Interface Signals.

MAC Interface Signal	Output From	Function
RxD	PHY	Data to the MAC is synchronously clocked by RX_CLK

MAC Interface Signal	Output From	Function
RxCk	PHY	Clock for RX DATA
TxD	MAC	Data to the PHY is synchronously clocked by TX_CLK
TxCk	PHY	Clock for TX DATA
TxEN	MAC	Transmit enable request from the MAC to begin sending data to the PHY.
CRS	PHY	Carrier Sense indicates the PHY is receiving a valid signal from the wiring network
COL	PHY	Collision. Indicates a collision was detected by the PHY on the wiring network

Devices connected to the network have the ability to detect whether they are connected to a “live” network or not by means of a valid link indication function.

- 5 HomePNA PHY 106 provides a valid link indication via signal Valid Link 302. Valid Link signal 302 may be provided to other layers or a management entity, and indicates whether link 110 is determined by PHY 106 to be functioning.

Each PHY on the network transmits a link frame if it has not transmitted a normal data frame or link frame for 2.0 seconds. The reception of a normal data PHY frame or a link frame causes a valid link indication. Non reception of data or link frames within a
10 time period of not less than 4.0 seconds causes Valid Link signal 302 to indicate an invalid link indication.

Link frames are obtained from link packets by appending a HomePNA header as described in reference to Fig. 2. Link packets are defined by the HomePNA to be either
15 runt packets, null-addressed packets, or self-addressed packets. Runt packets are less than 64 bytes in length. The HomePNA recommends that link packets be implemented as indicated in Table 2.

Table 2. Link Packets

Option 1: Runt Packet (14 bytes)

20

Field	Length	Description
Destination Address	6 bytes	The Destination address is either a NULL address (all zeros), or the originating station's MAC address.
Source Address	6 bytes	The Source address is either a NULL address (all zeroes), or the originating station's MAC address
Type/Length	2 bytes	The type/length field is set to a byte sequence value of 00-01 (hex). This value is an illegal length (not a type) that allows a promiscuous mode sniffer to determine that the runt is a HomePNA link frame.

Option 2: Minimum Sized Packet (64 bytes)

Field	Length	Description
Destination Address	6 bytes	The Destination address is either a NULL (all zeros), or the originating station's MAC address.
Source Address	6 bytes	The Source address is either a NULL address (all zeroes), or the originating station's MAC address
Type/Length	2 bytes	The Type/Length field is set to a byte sequence value of 00-2E (hex). This is a valid LLC length of 46 bytes.
LLC Test PDU Header	3 bytes	The DSAP field is set to a byte sequence value of 00-00-F3 (hex). This indicates a null-DSAP LLC test request frame.
Data	43 bytes	The data area of the link frame contains the following null terminated string: "HomePNA (version 1.1) Link heartbeat frame" This string allows promiscuous mode sniffers to determine that the frame is a HomePNA link frame.
CRC	4 bytes	Valid MAC CRC

Usually, the transmission of frames by a PHY requires a MAC layer. But for various market-demand reasons, it is desirable for a PHY to provide valid link indication functionality without assistance from a MAC or higher layer. This allows the use of Ethernet MAC chips that may not have valid link indication functionality built-in, and does not require the need to implement valid link indication functionality in software. The latter is important, not only because implementing valid link indication functionality in software may slow down system performance, but also because there may be power-saving states in which software will not work but for which link indication functionality is still needed. However, the requirement to have MAC functionality incorporated in a PHY is costly and leads to redundancy in devices that also have a MAC layer. It is therefore desirable for a PHY to have valid link indication functionality without the overhead of a MAC layer. There is also a need for a PHY to efficiently handle collisions between a link frame and a data frame, and between a link frame and another link frame. The present invention addresses these issues.

Brief Description of the Drawings

Fig. 1 illustrates the position of a HomePNA PHY within the OSI communication protocol stack.

Fig. 2 illustrates HomePNA PHY framing.

Fig. 3 illustrates a MAC-to-HomePNA PHY interface.

Fig. 4 provides a flow diagram for an embodiment of the present invention.

Fig. 5 provides a portion of the PHY architecture for an embodiment of the present invention.

Description of Embodiments

Fig. 4 diagrams a method implemented by a HomePNA PHY according to an embodiment of the present invention. In Fig. 4, step 402 tests for whether a frame has been transmitted for the last 2.0 seconds. If no transmission has occurred in the last 2.0 seconds, then in step 404 the TxClk signal is stopped so that MAC 104 does not request PHY 106 to transmit a MAC frame, and a link frame is transmitted.

During transmission of the link frame in step 404, step 406 determines whether a collision is detected. If no collision is detected during transmission of the link frame, then the TxClk signal is enabled in step 407 so that MAC 104 is enabled to request transmission of MAC frames, and control is brought back to step 402. If a collision is detected, then a counter for keeping track of the number of collisions, referred to as Num_Col, is set to zero in step 408, and control is brought to step 410.

In step 410 the link frame is re-transmitted after waiting an interval of time equal to IPG, the minimum Inter Packet Gap. Step 412 determines whether a collision is detected during re-transmission of the link frame. If there is no collision, then the TxClk signal is enabled in step 407 and control is brought back to step 402. If there is a collision, control is brought to step 414, whereupon the counter Num_Col is incremented by one.

After Num_Col is incremented by one in step 414, step 416 determines whether it is less than a positive integer N . If Num_Col is less than N , control is brought back to step 410, whereupon the link frame is again re-transmitted after waiting an IPG. If, however, Num_Col is no longer less than N in step 416, then control is brought to step 417 rather than looping back to step 410.

The loop defined by steps 410, 412, 414, and 416 causes a colliding link frame to be re-transmitted, with each re-transmission separated by an IPG, until either a collision-free link frame transmission has been accomplished, or until N re-transmissions have been made. Thus, counting the initial link frame transmission in step 404, when a link frame collides with another frame from another PHY, a sequence of back-to-back link

frames, each separated by an IPG, will be transmitted, up to a maximum number of $N+1$ link frames. The integer N may be distinct for each HomePNA PHY, or may be the same for all HomePNA PHYs.

Once the number of re-transmissions for a colliding link frame has reached N (Num_Col is no longer less than N in step 416), the TxClk signal is enabled in step 417 so that MAC 104 may request PHY 106 to transmit a MAC frame, and a random time interval is allowed to elapse in step 418 before control is brought back to step 402. The randomization provided in step 418 prevents a live-lock condition in which two colliding PHYs are each attempting to transmit a link frame.

Because step 410 re-transmits a colliding link frame after waiting only for an IPG, re-transmission of a colliding link frame is given higher priority than the re-transmission of a colliding data frame governed by the random process used for Ethernet, known as the truncated binary exponential backoff.

Fig. 5 provides a portion of the PHY architecture for an embodiment of the present invention. Finite state machine (FSM) 502 implements the flow diagram of Fig. 4. For simplicity, only the TxClk signal and Valid Link signal 302 are shown in Fig. 5. Counter 514 stores the value of Num_Col as described in reference to Fig. 4. Collision detector 504 indicates to FSM 502 whether a collision is detected, and FSM 502 indicates to transceiver 512 when a link packet is to be transmitted according to the flow diagram of Fig. 4.

The random time interval generated in step 418 of Fig. 4 may be realized in Fig. 5 by ring oscillator 506, free-running counter 508, and latch 510. Ring oscillator 506 provides a clock signal to free-running counter 508, and is designed so that its frequency, and hence the clock signal used to clock counter 508, is a function of temperature, process, or other environmental factors. Counter 508 is sampled and latched by latch 510 to provide a random number. FSM 502 uses the random number stored in latch 510 to determine the random time interval in step 418.

FSM 502 may be realized by a programmable logic device, or an application specific integrated circuit. FMS 502 may also be realized by a programmable processor responsive to instructions stored as software or firmware. Various modifications may be made to the described embodiments without departing from the scope of the invention as

claimed below. For example, another embodiment may follow the flow diagram in Fig. 4, with the exception that if step 416 is answered in the negative, step 417 is not implemented, and after step 418, Num_Col is re-set to zero and control is brought immediately to step 410 rather than to step 402. In another embodiment, a time interval
5 other than IPG may be used in step 410. For example, a positive random variable may be added to IPG before re-transmitting a link frame in step 410, so that a collision among colliding link frames may be more quickly resolved. However, such an approach may not give maximum priority to link frame re-transmission.

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What is claimed is:

1. A method for a PHY to resolve link frame collisions, the method comprising:
 - (i) attempting to transmit a link frame if the PHY has not transmitted a frame in the last x seconds, where x is a positive real number; and
 - (ii) if a frame collision is detected during step (i), attempting to transmit a link frame at a time interval after the last frame transmission attempt of the PHY has ended.
2. The method as set forth in claim 1, further comprising:
 - (iii) repeating claim limitation (ii) each time a frame collision is detected until the number of link frame transmission attempts since the occurrence of claim limitation (i) equals a specified limit.
3. The method as set forth in claim 2, further comprising:
 - (iv) if in performing claim limitation (iii) the number of link frame transmission attempts since the occurrence of claim limitation (i) equals the specified limit, performing claim limitations (i) and (ii) upon allowing a random interval of time to elapse after the last link frame transmission attempt of the PHY has ended.
4. The method as set forth in claim 1, wherein the time interval is an Inter Packet Gap (IPG).
5. The method as set forth in claim 4, further comprising:

Variable	Mean	SD	Min	Max
Age	34.5	10.2	21	55
Gender	1.2	0.4	1	2
Marital status	1.5	0.5	1	3
Education	12.5	1.5	9	16
Income	1.8	0.8	1	3
Occupation	1.5	0.5	1	3
Religion	1.2	0.4	1	2
Political affiliation	1.5	0.5	1	3
Health status	1.5	0.5	1	3
Life satisfaction	1.5	0.5	1	3
Self-esteem	1.5	0.5	1	3
Depression	1.5	0.5	1	3
Anxiety	1.5	0.5	1	3
Stress	1.5	0.5	1	3
Resilience	1.5	0.5	1	3
Optimism	1.5	0.5	1	3
Gratitude	1.5	0.5	1	3
Forgiveness	1.5	0.5	1	3
Empathy	1.5	0.5	1	3
Compassion	1.5	0.5	1	3
Kindness	1.5	0.5	1	3
Generosity	1.5	0.5	1	3
Patience	1.5	0.5	1	3
Humility	1.5	0.5	1	3
Modesty	1.5	0.5	1	3
Shyness	1.5	0.5	1	3
Introversion	1.5	0.5	1	3
Extroversion	1.5	0.5	1	3
Sensitivity	1.5	0.5	1	3
Emotionality	1.5	0.5	1	3
Imagination	1.5	0.5	1	3
Creativity	1.5	0.5	1	3
Curiosity	1.5	0.5	1	3
Openness	1.5	0.5	1	3
Conscientiousness	1.5	0.5	1	3
Agreeableness	1.5	0.5	1	3
Neuroticism	1.5	0.5	1	3
Stability	1.5	0.5	1	3
Control	1.5	0.5	1	3
Order	1.5	0.5	1	3
Discipline	1.5	0.5	1	3
Perseverance	1.5	0.5	1	3
Endurance	1.5	0.5	1	3
Strength	1.5	0.5	1	3
Power	1.5	0.5	1	3
Influence	1.5	0.5	1	3
Leadership	1.5	0.5	1	3
Authority	1.5	0.5	1	3
Control	1.5	0.5	1	3
Order	1.5	0.5	1	3
Discipline	1.5	0.5	1	3
Perseverance	1.5	0.5	1	3
Endurance	1.5	0.5	1	3
Strength	1.5	0.5	1	3
Power	1.5	0.5	1	3
Influence	1.5	0.5	1	3
Leadership	1.5	0.5	1	3
Authority	1.5	0.5	1	3
Control	1.5	0.5	1	3
Order	1.5	0.5	1	3
Discipline	1.5	0.5	1	3
Perseverance	1.5	0.5	1	3
Endurance	1.5	0.5	1	3
Strength	1.5	0.5	1	3
Power	1.5	0.5	1	3
Influence	1.5	0.5	1	3
Leadership	1.5	0.5	1	3
Authority	1.5	0.5	1	3
Control	1.5	0.5	1	3
Order	1.5	0.5	1	3
Discipline	1.5	0.5	1	3
Perseverance	1.5	0.5	1	3
Endurance	1.5	0.5	1	3
Strength	1.5	0.5	1	3
Power	1.5	0.5	1	3
Influence	1.5	0.5	1	3
Leadership	1.5	0.5	1	3
Authority	1.5	0.5	1	3
Control	1.5	0.5	1	3
Order	1.5	0.5	1	3
Discipline	1.5	0.5	1	3
Perseverance	1.5	0.5	1	3
Endurance	1.5	0.5	1	3
Strength	1.5	0.5	1	3
Power	1.5	0.5	1	3
Influence	1.5	0.5	1	3

(iv) if in performing claim limitation (iii) the number of link frame transmission attempts since the occurrence of claim limitation (i) equals the specified limit, performing claim limitations (i) and (ii) upon allowing a random interval of time to elapse after the last link frame transmission attempt of the PHY has ended.

a transceiver to transmit and receive frames on a network; and

a finite state machine; wherein

while the finite state machine is in a first state, the PHY monitors frame transmissions by the transceiver; and

while the finite state machine is in a second state, the PHY attempts link frame transmissions such that each link frame transmission is attempted at a time interval after the last frame transmission attempt has ended.

while the finite state machine is in a third state, the PHY does not transmit any link frames, wherein the finite state machine transitions from the third state to the first state after a random time interval upon entering the third state;

the finite state machine transitions from the first state to the second state if there has been no frame transmission for a time period;

the finite state machine causes the transceiver to attempt to transmit a link frame when transitioning from the first state to the second state; and

the finite state machine transitions from the second state to the first state if no frame collision is detected since the last frame transmission attempt.

9. The PHY as set forth in claim 8, wherein

the finite state machine transitions from the second state to the third state if the number of link frame transmissions since entering the second state is equal to a specified limit.

10. The PHY as set forth in claim 9, wherein

while the finite state machine is in the first state and the third state, a PHY-to-MAC transmit-clock signal is enabled; and

while the finite state machine is in the second state, the PHY-to-MAC transmit-clock signal is disabled.

11. The PHY as set forth in claim 7, wherein the time interval is an Inter Packet Gap (IPG).

12. The PHY as set forth in claim 11, wherein

while the finite state machine is in a third state, the PHY does not transmit any link frames, wherein the finite state machine transitions from the third state to the first state after a random time interval upon entering the third state;

the finite state machine transitions from the first state to the second state if there has been no frame transmission for a time period;

the finite state machine causes the transceiver to attempt to transmit a link frame when transitioning from the first state to the second state; and

the finite state machine transitions from the second state to the first state if no frame collision is detected since the last frame transmission attempt.

13. The PHY as set forth in claim 12, wherein

the finite state machine transitions from the second state to the third state if the number of link frame transmissions since entering the second state is equal to a specified limit.

14. The PHY as set forth in claim 13, wherein

while the finite state machine is in the first state and the third state, a PHY-to-MAC transmit-clock signal is enabled; and

while the finite state machine is in the second state, the PHY-to-MAC transmit-clock signal is disabled.

15. A PHY comprising:

a transceiver to attempt to transmit a first link frame if the PHY has not transmitted a frame for a time period; and

a collision detector, wherein if a first collision is detected by the collision detector during the attempt to transmit the first link frame, the PHY attempts to transmit a second link frame a time interval equal to an Inter Packet Gap (IPG) after transmission of the first link frame.

16. The PHY as set forth in claim 15, further comprising:

a counter, wherein the counter is changed by an increment if the collision detector detects a second collision when the PHY attempts to transmit the second link frame.

17. The PHY as set forth in claim 16, further comprising:

a free-running counter; and

an oscillator to clock the free-running counter, wherein the free-running counter provides a random number so that if the counter is equal to a specified limit when another frame collision is detected, a random time interval is allowed to elapse before another link frame is attempted to be transmitted.

18. A communication system comprising:

a network comprising a home phone line; and

a PHY coupled to the network to transmit and receive frames, the PHY comprising:

a transceiver to attempt to transmit a first link frame if the PHY has not transmitted a frame for a time period; and

a collision detector, wherein if a first collision is detected by the collision detector during the attempt to transmit the first link frame, the PHY attempts to transmit a second link frame a time interval equal to an Inter Packet Gap (IPG) after transmission of the first link frame.

19. The communication system as set forth in claim 18, wherein the PHY further comprises:

a counter, wherein the counter is changed by an increment if the collision detector detects a second collision when the PHY attempts to transmit the second link frame.

20. The communication system as set forth in claim 19, wherein the PHY further comprises:

a free-running counter; and

an oscillator to clock the free-running counter, wherein the free-running counter provides a random number so that if the counter is equal to a specified limit when another frame collision is detected, a random time interval is allowed to elapse before another link frame is attempted to be transmitted.

Abstract

A PHY for transmitting link frames on a home phone line network without the need of a MAC layer. The PHY transmits an initial link frame if the PHY has not transmitted a frame for a time interval, as specified by the Home Phoneline Networking Alliance. After transmission of the initial link frame, the transmit-clock signal to the MAC is disabled so that the MAC does not request the PHY to transmit a frame. If a collision is detected during transmission of the initial link frame, a counter is set to zero and the PHY transmits back-to-back link frames, where the initial link frame and the back-to-back link frames are each separated by an IPG (Inter Packet Gap). When transmitting these back-to-back link frames, the counter is incremented each time a collision is detected. When the counter equals a specified number, the transmit-clock signal to the MAC is enabled and the PHY waits for a random interval of time before beginning the above-described process again. This process is repeated until a link frame is successfully transmitted without a collision. In this way, higher priority is given to colliding link frames than to colliding data frames, and the case of colliding link frames is efficiently handled by the randomization process so that a live-lock situation is prevented.

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[illegible]

Fig. 2 (Prior Art)

DECEMBER 2006

MAC to Home PNA PHY Interface

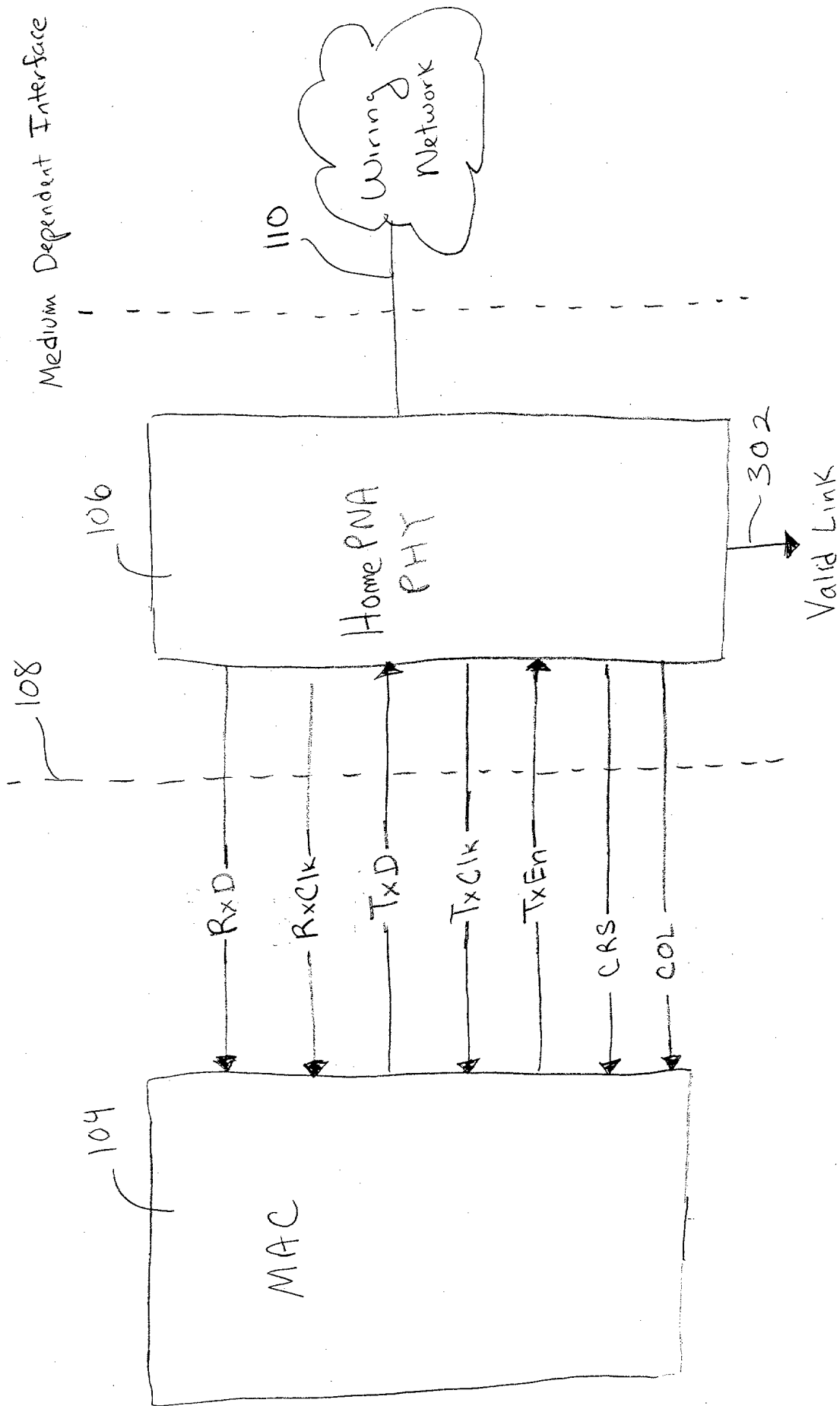


Fig. 3 (Prior Art)

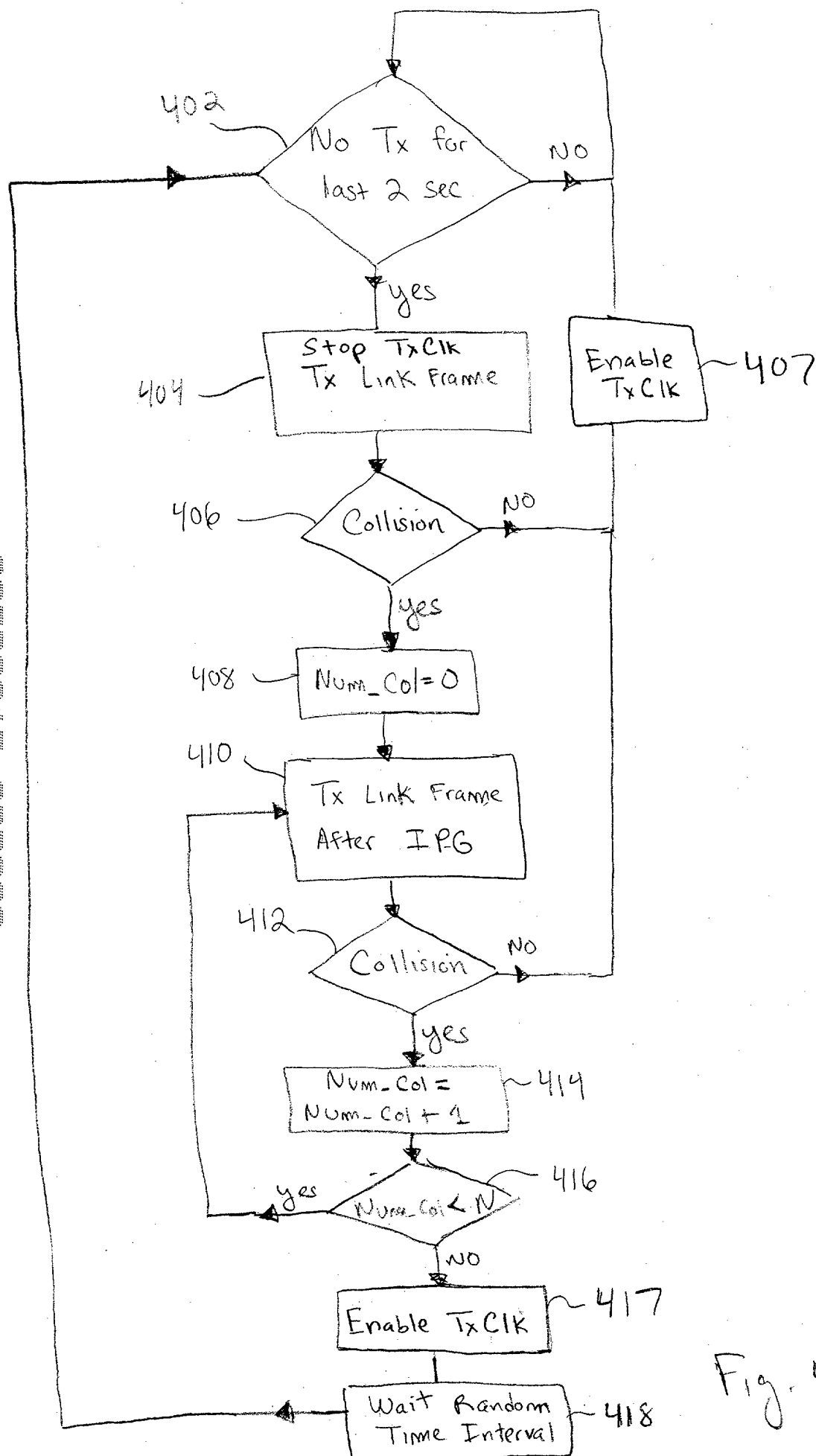
[illegible]

Fig. 4

